

User Manual

[SBC-EC9100]

Revision History

Rev.	Note	Author
20160907	Initial	Sandy

Catalog

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Release Note

1. Images Version

91200003_SBC-EC9100-SDcard_Shipment_Image_REV00.img

91200003_SBC-EC9100-EMMC_Shipment_Image_REV00.img

2. Feature List

Feature List	SBC-EC9100			Detail Functions(Needed)
	Schematic Page#	On-Chip Peripherals	On-Board Peripherals	
u-boot version	2015.04			Can only boot the kernel
kernel version	3.14.52			Kernel will support all the function below
Filesystem	buildroot			buildroot of embest own
CPU	EC9100-U2	imx6ul		
DDRAM	EC9100-U7	DDR3	MT41K256M16HA-125	Can access read write and run code
MicroSD_(TF)	EC9100-J3	MMC0	Null	Can access read write and boot
eMMC	EC9100-U6	MMC1		Can access read write
UART-0		UART1		System can send and receive data in loopback mode
UART-1		RS485		System can send and receive data in loopback mode
UART-2		UART3		Debug Serial
PMIC	EC9100-U3	I2C0	PZUFE3001	
Ethernet-1	EC9100-U8	RGMII1	KSZ8081RNXIA	
USB-Host	EC9100-J7	USB1		Can recognize U disk by USB host
USB-OTG	EC9100-J8	USB0	Null	Can recognize U disk by USB host
LCD	EC9100-J5	RGB	Null	Can show picture on the screen
Backlight	EC9100-U24	PWM	Null	System can control the LCD backlight
Touchscreen	EC9100-J5	ADC-TSC	Null	
EEPROM	EC9100-U25	I2C0	AT24C256W	Can access read write

CAN-1	EC9100-u14	CAN1	mc33901wef	System can send and receive data in loopback mode
CAN-2	EC9100-U17	CAN0	mc33901wef	System can send and receive data between two board
RS485-1	EC9100-MN 1	UART1	ADM3485	System can send and receive data between two board
debian filesystem				
ADC		Null	Null	
CAMERA		CSI&I2C1	Null	
WIFI	EC9100-U21	SDIO2	Null	
SPI		SPI3	Null	

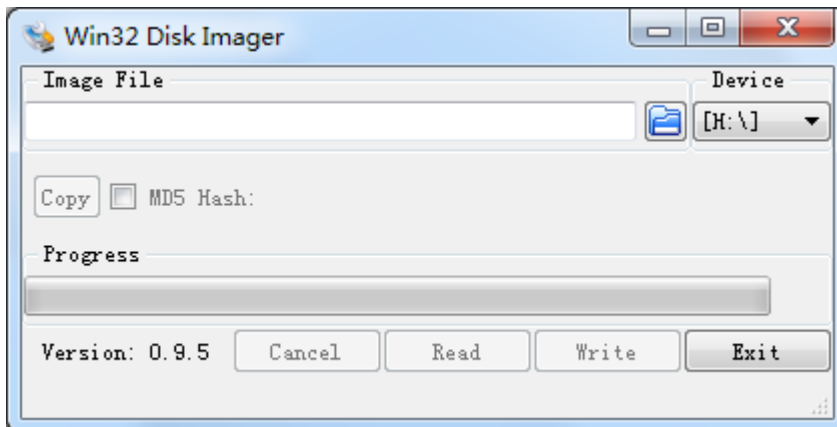
3. Known Issues

1. The highest resolution of Camera is 720*576 resolution.
2. Wifi module is selectable ,but now cannot work;

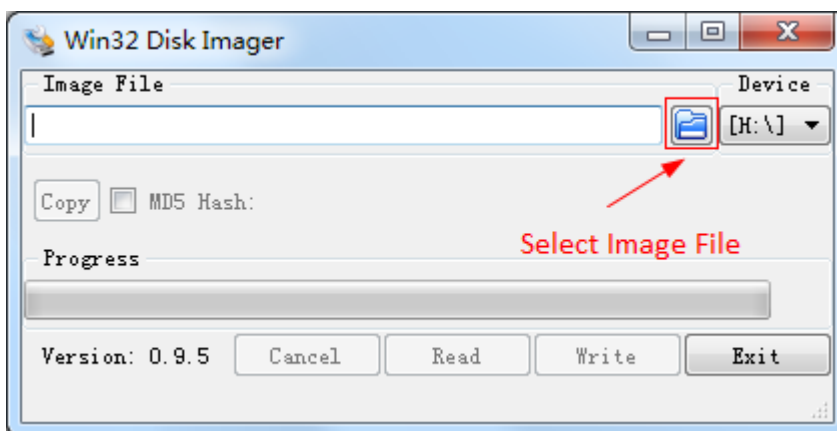
Chapter 1 Quick Start

1.1 Burn the System Images to the SD Card

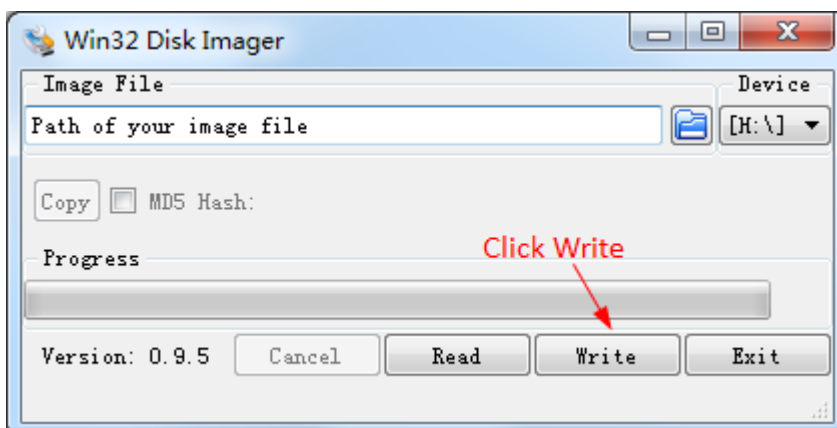
- Firstly, you should prepare a SD card, which is no less than 1GB.
- Then, download and install “Win32 Disk Imager” from <https://sourceforge.net/projects/win32diskimager/>.



- Select the system images file: 91200003_SBC-EC9100-SDcard_Shipment_Image_REV00.img



- Click “Write” button to burn the images:



1.2 System Boot from SD Card

- Install the Serial Communication software (e.g. SecureCRT), select the corresponding port number, baudrate as 115200, data bits as 8, stop bits as 1, parity as none.
- Connect the Uart Tx (Pin 8 in J10) and Rx (Pin 10 in J10) to PC with USB to TTL convertor.
- Insert the SD card into the card slot J3.
- Powered the board with a 5V, 2A power (J1).
- Change the dial switch SW3 to 00, SW4 to 0010.
- Wait for the system boot up, then the serial output will show the following information:

```
[ OK ] started system Logging Service.  
      Starting Getty on tty1...  
[ OK ] started Getty on tty1.  
      Starting Serial Getty on ttymxc2...  
[ OK ] started Serial Getty on ttymxc2.  
[ OK ] Reached target Login Prompts.  
[ OK ] Started Embest AutoExec Service.  
[ OK ] Started Login Service.
```

```
Debian GNU/Linux 8 embest ttymxc2
```

```
embest login: █
```

Enter username and password as “root” to login;

```
Debian GNU/Linux 8 embest ttymxc2
```

```
embest login: root
```

```
Password:
```

```
Linux embest 3.14.52 #1 SMP PREEMPT wed Aug 31 12:08:45 CST 2016 armv7l
```

```
The programs included with the Debian GNU/Linux system are free software;  
the exact distribution terms for each program are described in the  
individual files in /usr/share/doc/*/copyright.
```

```
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent  
permitted by applicable law.
```

```
root@embest:~#
```


1.3 System Boot from EMMC

Copy the 91200003_SBC-EC9100-EMMC_Shipment_Image_REV00.img to a U-disk;

Refer to [1.2](#), boot the system from SD Card, then plug the U disk to USB interface J8:

Execute the following instructions on the serial terminal:

```
root@embest:~# ls /dev/sd*
```

```
/dev/sda /dev/sda1
```

```
root@embest:~# mount /dev/sda1 /mnt/
```

```
root@embest:~# dd if=/mnt/91200003_SBC-EC9100-EMMC_Shipment_Image_REV00.img of=/dev/mmcblk1
```

Note: Burn the EMMC takes a long time, please wait patiently.

If it is the first time to burn the EMMC, you need to Enable boot from EMMC user partition, [see chapter 3.2.3](#).

Then you don't need to do this operation anymore.

Power off the board after the burning finished, change the dial switch SW3 to 10, SW4 to 0110, plug out the SD card, power on the board to boot from EMMC

Chapter 2 Function test

First of all, please refer to [Chapter 1.1](#) and boot up the system. Then test the functions according to the following guidance.

2.1 Button

Insert the micro SD card to SBC-EC9100, power on the board, boot the system.

Press the RESET after system boot, it will reboot the system.

Push ON/OFF for more than 8 seconds, system will halt, then push 8 seconds again, system will reboot.

Users can also test it using the following instructions:

```
root@embest:~# evtest /dev/input/event0
```

```
Input driver version is 1.0.1
```

```
Input device ID: bus 0x19 vendor 0x0 product 0x0 version 0x0
```

```
Input device name: "20cc000.snvs-pwrkey"
```

```
Supported events:
```

```
Event type 0 (EV_SYN)
```

```
Event type 1 (EV_KEY)
```

```
Event code 116 (KEY_POWER)
```

```
Properties:
```

```
Testing ... (interrupt to exit)
```

Press the button:

```
Event: time 1469459707.798194, type 1 (EV_KEY), code 116 (KEY_POWER), value 1
```

```
Event: time 1469459707.798194, ----- EV_SYN -----
```

```
Event: time 1469459708.038234, type 1 (EV_KEY), code 116 (KEY_POWER), value 0
```

```
Event: time 1469459708.038234, ----- EV_SYN -----
```

```
Event: time 1469459710.058188, type 1 (EV_KEY), code 116 (KEY_POWER), value 1
```

```
Event: time 1469459710.058188, ----- EV_SYN -----
```

```
Event: time 1469459710.238220, type 1 (EV_KEY), code 116 (KEY_POWER), value 0
```

```
Event: time 1469459710.238220, ----- EV_SYN -----
```

2.2 RTC

Connect the battery module to the board, then execute the following instructions on the serial terminal:

Check the current system time:

```
root@embest:~# date
```

```
Sat Jan 1 00:02:07 UTC 2000
```

Set current time as 10:46, March 9, 2016

```
root@embest:~# date 030910462016
```

```
Wed Mar 9 10:46:00 UTC 2016
```

Write system clock into RTC:

```
root@embest:~# hwclock -w
```

Read RTC value:

```
root@embest:~# hwclock
```

```
Wed 09 Mar 2016 10:46:23 AM UTC -0.432561 seconds
```

The above information indicates that the hardware clock-RTC-has been set to March 9, 2016, so the system clock is saved in the hardware clock.

Reboot the system and check the current system time:

```
root@embest:~# date
```

```
Wed Mar 9 10:46:45 UTC 2016
```

2.3 EEPROM

Execute the following instructions on the serial terminal:

```
root@embest:~# ./eeprom_test
```

```
data will write to EEPROM at 0x400
```

```
00 01 02 03 04 05 06 07 08 09 0a 0b 0c 0d 0e 0f
10 11 12 13 14 15 16 17 18 19 1a 1b 1c 1d 1e 1f
20 21 22 23 24 25 26 27 28 29 2a 2b 2c 2d 2e 2f
30 31 32 33 34 35 36 37 38 39 3a 3b 3c 3d 3e 3f
40 41 42 43 44 45 46 47 48 49 4a 4b 4c 4d 4e 4f
50 51 52 53 54 55 56 57 58 59 5a 5b 5c 5d 5e 5f
60 61 62 63 64 65 66 67 68 69 6a 6b 6c 6d 6e 6f
70 71 72 73 74 75 76 77 78 79 7a 7b 7c 7d 7e 7f
```

```
80 81 82 83 84 85 86 87 88 89 8a 8b 8c 8d 8e 8f
90 91 92 93 94 95 96 97 98 99 9a 9b 9c 9d 9e 9f
a0 a1 a2 a3 a4 a5 a6 a7 a8 a9 aa ab ac ad ae af
b0 b1 b2 b3 b4 b5 b6 b7 b8 b9 ba bb bc bd be bf
c0 c1 c2 c3 c4 c5 c6 c7 c8 c9 ca cb cc cd ce cf
d0 d1 d2 d3 d4 d5 d6 d7 d8 d9 da db dc dd de df
e0 e1 e2 e3 e4 e5 e6 e7 e8 e9 ea eb ec ed ee ef
f0 f1 f2 f3 f4 f5 f6 f7 f8 f9 fa fb fc fd fe ff
```

data read from EEPROM at 0x400

```
00 01 02 03 04 05 06 07 08 09 0a 0b 0c 0d 0e 0f
10 11 12 13 14 15 16 17 18 19 1a 1b 1c 1d 1e 1f
20 21 22 23 24 25 26 27 28 29 2a 2b 2c 2d 2e 2f
30 31 32 33 34 35 36 37 38 39 3a 3b 3c 3d 3e 3f
40 41 42 43 44 45 46 47 48 49 4a 4b 4c 4d 4e 4f
50 51 52 53 54 55 56 57 58 59 5a 5b 5c 5d 5e 5f
60 61 62 63 64 65 66 67 68 69 6a 6b 6c 6d 6e 6f
70 71 72 73 74 75 76 77 78 79 7a 7b 7c 7d 7e 7f
80 81 82 83 84 85 86 87 88 89 8a 8b 8c 8d 8e 8f
90 91 92 93 94 95 96 97 98 99 9a 9b 9c 9d 9e 9f
a0 a1 a2 a3 a4 a5 a6 a7 a8 a9 aa ab ac ad ae af
b0 b1 b2 b3 b4 b5 b6 b7 b8 b9 ba bb bc bd be bf
c0 c1 c2 c3 c4 c5 c6 c7 c8 c9 ca cb cc cd ce cf
d0 d1 d2 d3 d4 d5 d6 d7 d8 d9 da db dc dd de df
e0 e1 e2 e3 e4 e5 e6 e7 e8 e9 ea eb ec ed ee ef
f0 f1 f2 f3 f4 f5 f6 f7 f8 f9 fa fb fc fd fe ff
```

If write and read data are the same, the test passes.

2.4 EMMC

Execute the following instructions on the serial terminal:

```
root@embest:~# touch emmc_read emmc_write
```

Modify emmc_write value:

```
root@embest:~# vi emmc_write
```

E.g. Write “emmc write test” into the system

Write emmc instructions:

```
root@embest:~# dd if=emmc_write of=/dev/mmcblk1
```

```
mmcblk1: p1 p2
```

```
0+1 records in
```

```
0+1 records out
```

```
16 bytes (16 B) copied, 0.0396547 s, 0.4 kB/s
```

Read emmc instructions:

```
root@embest:~# dd if=/dev/mmcblk1 of=emmc_read bs=1K count=10
```

```
10+0 records in
```

```
10+0 records out
```

```
10240 bytes (10 kB) copied, 0.0179817 s, 569 kB/s
```

Check emmc_read value:

```
root@embest:~# cat emmc_read
```

```
emmc write test
```

Test passes;

2.5 GPIO

SBC-EC9100 have 4 pins which can be used as GPIO controlled output, they are:

- GPIO4 (Pin 8 in J9)
- GPIO5 (Pin 7 in J9)
- GPIO9 (Pin 23 in J9)
- GPIO132 (Pin 7 in J10)

Users can execute the following instruction to test GPIO function:

Example: Test GPIO4

1. Enable the GPIO and initialize it:

```
root@embest:~# echo 4 > /sys/class/gpio/export
```

```
root@embest:~# echo out > /sys/class/gpio/gpio4/direction
```

2. Set the level of pin and test the voltage of the pin:

```
root@embest:~# echo 1 > /sys/class/gpio/gpio4/value
```

Now the pin output should be high level

```
root@embest:~# echo 0 > /sys/class/gpio/gpio4/value
```

Now the pin output should be low level

Change the “4” to 5, 9, 132 in above instructions to test GPIO5 (Pin 7 in J9), GPIO9 (Pin 23 in J9) and GPIO132 (Pin 7 in J10).

2.6 LCD

Connect the screen module to J5,

4.3” LCD:

Open the uEnv.txt file from SD card, modify fdtfile=embest_fsl_sbc_ec9100_4.3inch.dtb

Then reboot the system;

7” LCD:

Open the uEnv.txt file from SD card, modify fdtfile=embest_fsl_sbc_ec9100_7inch.dtb

Then reboot the system;

Backlight test:

Execute the following instruction in the serial terminal

```
root@embest:~# echo 0 > /sys/class/backlight/backlight.9/brightness
```

echo from 0 to 7 to find the screen backlight change.

2.7 Touchscreen

Connect the screen module to J5, make sure fuse is written. Read the fuse value by the following instruction. (You just need to set bit 20 and bit21 to 1, eg. 0x003000xx)

```
root@embest:~# cat /sys/fsl_otp/HW_OCOTP_CFG2
```

To set fuse value, execute the following instruction (xx change to the value you cat):

```
root@embest:~# echo 0x003000xx > /sys/fsl_otp/HW_OCOTP_CFG2
```

Note: The value of different board may not be same, but it has no influence on the test.

Enter the following instruction to make the touch calibrate function work:

```
root@embest:~# export TSLIB_TSDEVICE=/dev/input/event1
```

execute the following instructions on the serial terminal to implement the touch screen calibration program:

```
root@embest:~# ts_calibrate
```

Following the notes on LCD, click the “+” icon for five times to complete the calibration.

2.8 Serial

The board has 2 serial interfaces, while the UART-3 is the debug interface. Short connect J203 to configure the iomux IC working at UART & CAN mode.

2.8.1 Loopback

UART2 test, short connect Pin 20 and 22 in J9:

Execute the following instructions on the serial terminal:

```
root@embest:~# ./uart_test -d /dev/ttymx1 -b 115200
```

```
/dev/ttymx1 SEND: 1234567890
```

```
/dev/ttymx1 RECV 10 total
```

```
/dev/ttymx1 RECV: 1234567890
```

2.8.2 Board to Board

Use two SBC-EC9100 boards, connect the Rx pin (22 in J9) with the Tx pin of the other board (Pin 20 in J9), Tx pin to the Rx pin of the other board.

Execute the following instructions on the serial terminal for each board:

```
root@embest:~# ./uart_test -d /dev/ttymx1 -b 115200
```

Two boards will both send and receive data.

The serial terminal will print the following info:

```
/dev/ttymx1 SEND: 1234567890
```

```
/dev/ttymx1 RECV 10 total
```

```
/dev/ttymx1 RECV: 1234567890
```

```
.....
```

Note: Press "CTRL+C" to exit the serial test.

2.9 RS485

Use two SBC-EC9100 boards to make the test, connect the pin 39 and 40 on board to the other board, then:

Execute the following instructions on board A:

```
root@embest:~# ./uart_test2 /dev/ttymx0 9600 0 100
```

Execute the following instructions on board B:

```
root@embest:~# ./uart_test2 /dev/ttymx0 9600 1
```

If test passed, board B will receive info like following:

```
*****data length = 31 *****
```

```
41 54 31 32 33 34 35 36 37 38 39 58 59 5a 61 62 63 64 65 64 66 68 69 6a 6b 6c 6d 6e 0d 00 fb
```

```
***** receive data 135667 pkts...0 bytes.....
```

Then switch the execute instruction.

2.10 CAN

Connect CAN0 with CAN1 by connect Pin 33 to Pin 34, Pin 35 to Pin 36 in J9.

Test method as below:

1. Open CAN0 CAN1

```
root@embest:~# ip link set can0 type can bitrate 50000 triple-sampling on
```

```
root@embest:~# ip link set can1 type can bitrate 50000 triple-sampling on
```

```
root@embest:~# ip link set can0 up
```

```
flexcan 2090000.can can0: writing ctrl=0x27292085
```

```
root@embest:~# ip link set can1 up
```

```
flexcan 2094000.can can1: writing ctrl=0x27292085
```

2. Send and Receive

CAN1 receive data, CAN0 send data to CAN1, if the following info printed, the test passes:

```
root@embest:~# candump can1&
```

```
[4] 589
```

```
root@embest:~# cansend can0 123#01020304050607
```

```
can1 123 [7] 01 02 03 04 05 06 07
```

Use show command to check the status of CAN.

CAN0 Tx added 1 packet, 7 bytes. CAN1 Rx added 1 packet, 7 bytes.

```
root@embest:~# ip -d -s link show can0
```

```
2: can0: <NOARP,UP,LOWER_UP,ECHO> mtu 576 qdisc pfifo_fast state UNKNOWN mode DEFAULT group default qlen 10
```

```
link/can promiscuity 0
```

```
can <TRIPLE-SAMPLING> state ERROR-ACTIVE (berr-counter tx 0 rx 0) restart-ms 0
```

```
bitrate 50000 sample-point 0.866
```

```
tq 1333 prop-seg 6 phase-seg1 6 phase-seg2 2 sjw 1
```

```
flexcan: tseg1 4..16 tseg2 2..8 sjw 1..4 brp 1..256 brp-inc 1
```

```
clock 30000000
```

```
re-started bus-errors arbit-lost error-warn error-pass bus-off
```


0	0	0	0	0	0
RX: bytes	packets	errors	dropped	overrun	mcast
0	0	0	0	0	0
TX: bytes	packets	errors	dropped	carrier	collsns
7	1	0	0	0	0

Note: Two CAN modules master be set at the same baudrate.

2.11 Network

Execute the following instructions on the serial terminal:

Configure the IP address:

```
root@embest:~# ifconfig eth0 192.168.2.64
```

Testing network interface:

```
root@embest:~# ping 192.168.2.1
```

2.12 USB

2.12.1 Host

2.12.1.1 U-disk

Insert the U-disk to the USB Host interface (J8), serial terminal will display the disk information:

```
usb 2-1: USB disconnect, device number 3
usb 2-1: new high-speed USB device number 4 using ci_hdrc
usb-storage 2-1:1.0: USB Mass Storage device detected
scsi0 : usb-storage 2-1:1.0
scsi 0:0:0:0: Direct-Access    Generic  Flash Disk           8.07 PQ: 0 ANSI: 4
sd 0:0:0:0: [sda] 7823360 512-byte logical blocks: (4.00 GB/3.73 GiB)
sd 0:0:0:0: [sda] Write Protect is off
sd 0:0:0:0: [sda] Write cache: disabled, read cache: enabled, doesn't support DPO or FUA
sda: sda1
sd 0:0:0:0: [sda] Attached SCSI removable disk
```

Execute the following instructions on the serial terminal:

```
root@embest:~# ls /dev/sd*
```

```
/dev/sda /dev/sda1
```

Storage nodes locate under /dev;

2.12.1.2 Keyboard

Connect USB Keyboard to the USB Host interface (J8), serial terminal will print as follows:

```
usb 2-1: new low-speed USB device number 3 using ci_hdrc
```

```
input: SIGMACH1P USB Keykoard as
```

```
/devices/soc0/soc.0/2100000.aips-bus/2184200.usb/ci_hdrc.1/usb2/2-1/2-1:1.0/0003:1C4F:0002.0003/input/inp  
ut4
```

```
hid-generic 0003:1C4F:0002.0003: input: USB HID v1.10 Keyboard [SIGMACH1P USB Keykoard] on
```

```
usb-ci_hdrc.1-1/input0
```

```
input: SIGMACH1P USB Keykoard as
```

```
/devices/soc0/soc.0/2100000.aips-bus/2184200.usb/ci_hdrc.1/usb2/2-1/2-1:1.1/0003:1C4F:0002.0004/input/inp  
ut5
```

```
hid-generic 0003:1C4F:0002.0004: input: USB HID v1.10 Device [SIGMACH1P USB Keykoard] on
```

```
usb-ci_hdrc.1-1/input1
```

Execute evtest command to test /dev/input/event2:

```
root@embest:~# evtest /dev/input/event2
```

```
Input driver version is 1.0.1
```

```
Input device ID: bus 0x3 vendor 0x1c4f product 0x2 version 0x110
```

```
Input device name: "SIGMACH1P USB Keykoard"
```

```
Supported events:
```

```
Event type 0 (EV_SYN)
```

```
Event type 1 (EV_KEY)
```

```
Event code 1 (KEY_ESC)
```

```
Event code 2 (KEY_1)
```

```
Event code 3 (KEY_2)
```

```
Event code 192 (KEY_F22)
```

```
Event code 193 (KEY_F23)
```

```
Event code 194 (KEY_F24)
```

```
Event code 240 (KEY_UNKNOWN)
```

```
Event type 4 (EV_MSC)
```

```
Event code 4 (MSC_SCAN)
```

Event type 17 (EV_LED)

Event code 0 (LED_NUML)

Event code 1 (LED_CAPSL)

Event code 2 (LED_SCROLLL)

Key repeat handling:

Repeat type 20 (EV_REP)

Repeat code 0 (REP_DELAY)

Value 250

Repeat code 1 (REP_PERIOD)

Value 33

Properties:

Testing ... (interrupt to exit)

Press the key of the key board, the corresponding data for the key will be printed:

Event: time 73542.642111, type 4 (EV_MSC), code 4 (MSC_SCAN), value 70017

Event: time 73542.642111, type 1 (EV_KEY), code 20 (KEY_T), value 1

Event: time 73542.642111, ----- EV_SYN -----

Event: time 73542.762091, type 4 (EV_MSC), code 4 (MSC_SCAN), value 70017

Event: time 73542.762091, type 1 (EV_KEY), code 20 (KEY_T), value 0

Event: time 73542.762091, ----- EV_SYN -----

Event: time 73544.202085, type 4 (EV_MSC), code 4 (MSC_SCAN), value 7000a

Event: time 73544.202085, type 1 (EV_KEY), code 34 (KEY_G), value 1

Event: time 73544.202085, ----- EV_SYN -----

Event: time 73544.290084, type 4 (EV_MSC), code 4 (MSC_SCAN), value 7000a

Event: time 73544.290084, type 1 (EV_KEY), code 34 (KEY_G), value 0

Event: time 73544.290084, ----- EV_SYN -----

2.12.2 OTG

Connect U-disk or USB keyboard to J7 with an OTG cable, test command and phenomenon is similar with [Host Test](#), while the USB id is different:

2.12.2.1 U-Disk

ci_hdrc ci_hdrc.0: timeout waiting for 00000800 in 12

ci_hdrc ci_hdrc.0: EHCI Host Controller

ci_hdrc ci_hdrc.0: new USB bus registered, assigned bus number 1

```
ci_hdrc ci_hdrc.0: USB 2.0 started, EHCI 1.00
hub 1-0:1.0: USB hub found
hub 1-0:1.0: 1 port detected
usb 1-1: new high-speed USB device number 2 using ci_hdrc
usb-storage 1-1:1.0: USB Mass Storage device detected
scsi1 : usb-storage 1-1:1.0
scsi 1:0:0:0: Direct-Access    Generic  Flash Disk    8.07 PQ: 0 ANSI: 4
sd 1:0:0:0: [sda] 7823360 512-byte logical blocks: (4.00 GB/3.73 GiB)
sd 1:0:0:0: [sda] Write Protect is off
sd 1:0:0:0: [sda] Write cache: disabled, read cache: enabled, doesn't support DPO or FUA
sda: sda1
sd 1:0:0:0: [sda] Attached SCSI removable disk
```

2.12.2.2 Keyboard

USB Keyboard:

```
usb 1-1: new low-speed USB device number 4 using ci_hdrc
input: SIGMACH1P USB Keykoard as
/devices/soc0/soc.0/2100000.aips-bus/2184000.usb/ci_hdrc.0/usb1/1-1/1-1:1.0/0003:1C4F:0002.0003/input/inp
ut4
hid-generic 0003:1C4F:0002.0003: input: USB HID v1.10 Keyboard [SIGMACH1P USB Keykoard] on
usb-ci_hdrc.0-1/input0
input: SIGMACH1P USB Keykoard as
/devices/soc0/soc.0/2100000.aips-bus/2184000.usb/ci_hdrc.0/usb1/1-1/1-1:1.1/0003:1C4F:0002.0004/input/inp
ut5
hid-generic 0003:1C4F:0002.0004: input: USB HID v1.10 Device [SIGMACH1P USB Keykoard] on
usb-ci_hdrc.0-1/input1
```

2.12.2.3 Slave Device

Connect J7 to PC, open the device manager, and check if the following device is recognized:



2.13 Camera

2.13.1 Record Video

Connect Camera module to J6, execute the following instructions on the serial terminal:

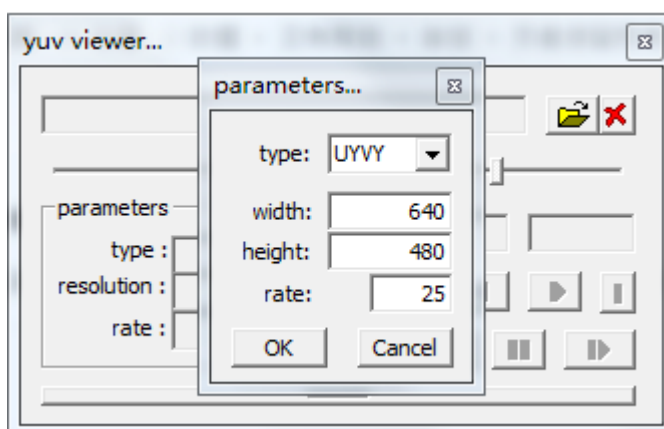
```
root@embest:~# ./mxc_v4l2_capture -iw 640 -ih 480 -ow 640 -oh 480 -c 25 -f UYVY /boot/firmware/test.yuv
```

```
root@embest:~# sync
```

Camera will record a video with 640*480 resolution, rate 25, generate the video file test.yuv in SD card folder.

Connect SD card to PC, open it with Pyuv.exe.

Parameters of Pyuv.exe should be set as follows:



Note: Pyuv.exe is provided from tool folder.

2.13.2 Record Photo

Connect screen and camera, then execute the following instructions on the serial terminal:

```
root@embest:~# ./v4l2_capture_jpeg img1.jpg
```

SBC-EC9100 will display the photo on screen.

Chapter 3 System Compilation

3.1 Building Development Environment

Copy the SBC-EC9100-Release-REV01 folder to Linux's \$HOME directory, while the compilation tool fsl-linaro-toolchain-master.tar.gz locate under path \$HOME/S5_Tool. Use the following instructions to extract it:

```
$tar -xzvf fsl-linaro-toolchain-master.tar.gz
```

Import the environment variable:

```
$export CROSS_COMPILE=$HOME/S5_Tool/fsl-linaro-toolchain-master/bin/arm-fsl-linux-gnueabi-
```

```
$export ARCH=arm
```

3.2 Compiling U-Boot

3.2.1 Get the U-Boot Source Code

U-boot source code locates under path \$HOME/S4_Sourcecode, extract the u-boot*.tar.gz:

```
$ cd $HOME/S4_Sourcecode
```

```
$ tar -xzvf u-boot*.tar.gz
```

3.2.2 Compile and Burn the Images to SD Card

```
$ cd $HOME/S4_Sourcecode/u-boot
```

```
$ make distclean
```

```
$make embest_fsl_ec9100_sdcard_defconfig
```

```
$make
```

When the compilation finished, it will generate a **u-boot.imx** under path \$HOME/S4_Sourcecode/u-boot. Burn this file to SD Card use dd command:

```
$ sudo dd if=u-boot.imx of=/dev/sdx bs=512 seek=2 conv=fsync
```

Note: You need to change sdx to the actual SD card name on your Linux system like sda, sdb, etc.

3.2.3 Compile and Burn the Images to EMMC

```
$ cd $HOME/S4_Sourcecode/u-boot
```

```
$ make distclean
```

```
$make embest_fsl_ec9100_emmc_defconfig
```

```
$make
```

When the compilation finished, it will generate a **u-boot.imx** under path \$HOME/S4_Sourcecode/u-boot. Copy the file to SD Card:

Refer to [1.2](#), first, you need to boot up the system from SD card. Then, type the following command on the system which already running on SD card to format and burn EMMC.

1. Prepare the EMMC partition

```
$ sudo dd if=/dev/zero of=/dev/mmcblk1 bs=1K count=1
```

```
$ echo -e " o\nn\np\n1\n20480\n+64M\na\nnt\nc\nnn\np\n2\n151552\n\n\n " | fdisk /dev/mmcblk1
```

```
$ sudo mkfs.vfat /dev/mmcblk1p1
```

```
$ sudo mkfs.ext4 /dev/mmcblk1p2
```

```
$ sudo fdisk /dev/mmcblk1 -l
```

2. Burn the u-boot.imx (for emmc) to EMMC use dd command

```
$ sudo dd if=u-boot.imx of=/dev/mmcblk1 bs=512 seek=2 conv=fsync
```

3. Enable boot from EMMC user partition

```
$ sudo echo 56 > /sys/block/mmcblk1/device/boot_config
```

4. Check whether the enable operation work

```
$ sudo cat /sys/block/mmcblk1/device/boot_info
```

If the operation works, it will print the following info:

```
boot_partition:0x78;
```

```
BOOT_ACK:1 - Boot acknowledge sent during boot operation
```

```
BOOT_PARTITION-ENABLE: 7 - User area enabled for boot
```

Now the U-boot is burned to EMMC

3.3 Kernel

3.3.1 Get Kernel Source Code

The source code of the kernel locate under \$HOME/S4_Sourcecode/, extract the linux*.tar.gz

```
$ tar -zxvf linux*.tar.gz
```

3.3.2 Compile and Burn the Images to SD Card

```
$ cd $HOME/S4_Sourcecode/linux
```

```
$ make distclean
```

```
$ make embest_fsl_sbc_ec9100_defconfig
```

```
$ make
```

When the compilation finished, it will generate

- zImage under \$HOME/S4_Sourcecode/linux/arch/arm/boot;
- following dtb files under \$HOME/ sourcecode/linux/arch/arm/boot/dts
 1. embest_fsl_sbc_ec9100_4.3inch.dtb
 2. embest_fsl_sbc_ec9100_7inch.dtb

The dtb file is corresponding for 4.3" LCD and 7" LCD. (Refer to [LCD test](#))

Copy the files to SD Card.